# Some characterizations of a class of balanced two-way elimination of heterogeneity designs

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### Summary

We characterize the variance balance and efficiency balance of a class of two-way elimination of heterogeneity designs in relation to the property of equal treatment replications and in relation to the corresponding balance properties of the treatment-row and treatment-column subdesigns.

# 1. Introduction and preliminaries

Consider a two-way elimination of heterogeneity design in which v treatments are allocated on n experimental units arranged in  $b_1$  rows and  $b_2$  columns. Let  $\mathbf{r} = (r_1, ..., r_v)'$ ,  $\mathbf{k}_1 = (k_{11}, ..., k_{1b_1})'$ , and  $\mathbf{k}_2 = (k_{21}, ..., k_{2b_2})'$  denote the vector of treatment replications, the vector of row sizes, and the vector of column sizes, respectively, and let  $\mathbf{R}$ ,  $\mathbf{K}_1$ , and  $\mathbf{K}_2$  be the diagonal matrices with the successive elements of  $\mathbf{r}$ ,  $\mathbf{k}_1$ , and  $\mathbf{k}_2$  on their diagonals. Moreover, let  $\mathbf{N}_1$  be the  $v \times b_1$  treatment-row incidence matrix, let  $\mathbf{N}_2$  be the  $v \times b_2$  treatment-column incidence matrix, and let  $\mathbf{N}_{12}$  be the  $b_1 \times b_2$  row-column incidence matrix.

A crucial role in the analysis of this design is played by the *C-matrix* defined by

$$\begin{split} \mathbf{C} &= \mathbf{R} - \mathbf{N}_1 \mathbf{K}_1^{-1} \mathbf{N}_1' - (\mathbf{N}_2 - \mathbf{N}_1 \mathbf{K}_1^{-1} \mathbf{N}_{12}) (\mathbf{K}_2 - \mathbf{N}_{12}' \mathbf{K}_1^{-1} \mathbf{N}_{12})^{-} (\mathbf{N}_2 - \mathbf{N}_1 \mathbf{K}_1^{-1} \mathbf{N}_{12})' \\ &= \mathbf{R} - \mathbf{N}_2 \mathbf{K}_2^{-1} \mathbf{N}_2' - (\mathbf{N}_1 - \mathbf{N}_2 \mathbf{K}_2^{-1} \mathbf{N}_{12}') (\mathbf{K}_1 - \mathbf{N}_{12} \mathbf{K}_2^{-1} \mathbf{N}_{12}')^{-} (\mathbf{N}_1 - \mathbf{N}_2 \mathbf{K}_2^{-1} \mathbf{N}_{12}')' \\ &, \end{split}$$

Key words: two-way elimination of heterogeneity design, row-column designs, efficiency-balance, variance-balance

where the minus superscript denotes any generalized inverse of a matrix; cf. Raghavarao and Federer (1975). The C-matrices of the two related subdesigns are

$$\mathbf{C}_h = \mathbf{R} - \mathbf{N}_h \mathbf{K}_h^{-1} \mathbf{N}_h'$$

with h = 1 for the treatment-row subdesign and h = 2 for the treatment-column subdesign, while the matrix  $C_0$  is defined as

$$\mathbf{C}_0 = \mathbf{R} - \mathbf{r}\mathbf{r}'/n \quad . \tag{1}$$

A two-way elimination of heterogeneity design is said to be connected if all treatment contrasts are unbiasedly estimable in the corresponding fixed linear model, for which it is necessary and sufficient that r(C) = v - 1, where r(C) denotes the rank of C. A two-way elimination of heterogeneity design is said to be variance-balanced if every normalized estimable treatment contrast is estimated in the corresponding linear model with the same variance. It is known [cf. Kshirsagar (1957) and Singh, Dey, and Nigam (1979)] that a connected two-way elimination of heterogeneity design is variance-balanced if and only if

$$C = \alpha Q_u$$
 for some  $\alpha > 0$ , (2)

where  $\mathbf{Q}_v = \mathbf{I}_v - \mathbf{1}_v \mathbf{1}_v' / v$  is the orthogonal projector on the ortho-complement of the subspace spanned by  $\mathbf{1}_v$ , the  $v \times 1$  vector of ones. A two-way elimination of heterogeneity design is said to be *efficiency-balanced* if every estimable treatment contrast is estimated in the corresponding linear model with the same efficiency. Following Williams (1975), we observe that a connected two-way elimination of heterogeneity design is efficiency-balanced if and only if

$$\mathbf{C} = \theta \mathbf{C}_0 \quad \text{for some} \quad \theta \in (0,1] ,$$
 (3)

where  $C_0$  is as defined in (1). The balance properties for the treatment-row and treatment-column subdesigns are defined analogously, and the criteria (2) and (3) modify to

$$\mathbf{C}_h = \alpha_h \mathbf{Q}_v \quad \text{for some} \quad \alpha_h > 0 \tag{4}$$

and

$$C_h = \theta_h C_0$$
 for some  $\theta_h \in (0,1)$ , (5)

respectively, where h = 1, 2.

For all connected two-way elimination of heterogeneity designs with equal row sizes, equal column sizes, and whose C matrices can be represented in the form

$$\mathbf{C} = \mathbf{R} - v_1 \mathbf{N}_1 \mathbf{N}_1' - v_2 \mathbf{N}_2 \mathbf{N}_2' + \rho \mathbf{r} \mathbf{r}' \quad \text{for some } v_1, v_2, \rho > 0 , \qquad (6)$$

some new results are derived concerning characterizations of the balance properties of a design in relation to the property of equal treatment replications and in relation to the corresponding balance properties of the treatment-row and treatment-column subdesigns.

It is known, that (6) may hold also for designs with equal row sizes and equal column sizes, which do not satisfy the condition

$$\mathbf{C} = \mathbf{C}_1 + \mathbf{C}_2 - \mathbf{C}_0$$

considered by Baksalary and Shah (1990). An example, with 7 treatments allocated in 7 rows and 7 columns, is given by

where the integers 1 through 7 denote distinct treatments and the asterisks indicate blanks; cf. Agrawal (1966). In this case  $C_1 = C_2 = (7/3)Q_7$  and  $C_0 = 3Q_7$ , thus yielding  $C_1 + C_2 - C_0 = (5/3)Q_7$ , whereas  $C = Q_7$ . But matrix C may be represented as in (6) with  $\rho=2/21$  and any  $\nu_1$  and  $\nu_2$  such that  $\nu_1 + \nu_2 = 1$ .

### 2. Properties of balanced designs

Singh, Dey, and Nigam (1979) gave the following characterization of balance of two-way elimination of heterogeneity designs.

Theorem 1. For a connected two-way elimination of heterogeneity design with the number of treatments  $v \ge 3$ , any two of the following properties imply the third property:

- (a) the design is efficiency-balanced,
- (b) the design is variance-balanced,
- (c) the design is equireplicated.

One of the topics of natural interest in the theory of two-way elimination of heterogeneity designs is investigating relationships between properties of a given design and the corresponding properties of its treatment-row and treatment-column subdesigns. If the property in question is the efficiency balance, then an immediate consequence of the criteria (3) and (5) is the following.

Theorem 2. For a connected two-way elimination of heterogeneity design with equal row sizes, equal column sizes, and such that  $C = \mathbf{R} - v_1 \mathbf{N}_1 \mathbf{N}_1' - v_2 \mathbf{N}_2 \mathbf{N}_2' + \rho \mathbf{r} \mathbf{r}'$  for some  $v_1$ ,  $v_2$ ,  $\rho > 0$ , any two of the following properties imply the third property:

- (a) the design is efficiency-balanced,
- (b) the treatment-row subdesign is efficiency-balanced,
- (c) the treatment-column subdesign is efficiency-balanced.

*Proof.* If the row sizes of the design are all equal to  $k_1$  and the column sizes are all equal to  $k_2$ , then condition (6), which may be reexpressed as

$$C = k_1 v_1 (\mathbf{R} - \mathbf{N}_1 \mathbf{N}_1' / k_1) + k_2 v_2 (\mathbf{R} - \mathbf{N}_2 \mathbf{N}_2' / k_2) - n\rho (\mathbf{R} - \mathbf{rr}' / n)$$

is equivalent to

$$\mathbf{C} = k_1 \mathbf{v}_1 \mathbf{C}_1 + k_2 \mathbf{v}_2 \mathbf{C}_2 - n\rho \mathbf{C}_0 . \tag{7}$$

In view of (7), the theorem is an immediate consequence of criteria (3) and (5).

Similarly as for efficiency-balanced designs, relationships between variance properties of a design and its subdesigns may be formulated.

Theorem 3. For a connected two-way elimination of heterogeneity design with the number of treatments  $v \ge 3$ , equal row sizes, equal column sizes, and such that  $C = \mathbf{R} - v_1 \mathbf{N}_1 \mathbf{N}_1' - v_2 \mathbf{N}_2 \mathbf{N}_2' + \rho \mathbf{r} \mathbf{r}'$  for some  $v_1, v_2, \rho > 0$ , any three of the following properties imply the fourth property:

- (a) the design is variance-balanced,
- (b) the treatment-row subdesign is variance-balanced,
- (c) the treatment-column subdesign is variance-balanced,
- (d) the design is equireplicated.

*Proof.* In view of (7), the theorem is an immediate consequence of criteria (2) and (4) and the fact that if  $v \ge 3$ , then  $C_0$  is proportional to  $Q_v$  if and only if the design is equireplicated.

It turns out that for the subclass of all two-way elimination of heterogeneity designs whose C-matrices have the representation (6), the part "(a) and (b)  $\Rightarrow$  (c)" of Theorem 1 may be substantially strengthened.

Theorem 4. For a connected two-way elimination of heterogeneity design with equal row sizes and column sizes, with the property that each of  $v \ge 3$  treatment occurs in each row as well as in each column at most once, and with the C-matrix of the form  $\mathbf{C} = \mathbf{R} - v_1 \mathbf{N}_1 \mathbf{N}_1' - v_2 \mathbf{N}_2 \mathbf{N}_2' + \rho \mathbf{r} \mathbf{r}'$  for some  $v_1, v_2, \rho > 0$ , consider the following statements:

- (a) the design is efficiency-balanced,
- (b) the design is variance-balanced,
- (c) the design is equireplicated.

Then (a)  $\Leftrightarrow$  (b)  $\land$  (c) and (b)  $\Leftrightarrow$  (a)  $\land$  (c).

*Proof.* The parts (b)  $\land$  (c)  $\Rightarrow$  (a) and (a)  $\land$  (c)  $\Rightarrow$  (b) are inherent in Theorem 1. If (a) holds, then combining (6) with (3) yields

$$\mathbf{R} - v_1 \mathbf{N}_1 \mathbf{N}_1' - v_2 \mathbf{N}_2 \mathbf{N}_2' + \rho \mathbf{r} \mathbf{r}' = \theta (\mathbf{R} - \mathbf{r} \mathbf{r}' / n) . \tag{8}$$

According to the assumption, the matrices  $N_1$  and  $N_2$  are binary, and therefore comparing the *i*-th diagonal elements on the two sides of (8) leads to the equality

$$r_i - v_1 r_i - v_2 r_i + \rho r_i^2 = \theta(r_i - r_i^2/n)$$
.

Hence it follows that  $r_i$  is independent of i, thus implying (c). If (b) holds, then combining (6) with (2) yields

$$\mathbf{R} - v_1 \mathbf{N}_1 \mathbf{N}_1' - v_2 \mathbf{N}_2 \mathbf{N}_2' + \rho \mathbf{r} \mathbf{r}' = \alpha (\mathbf{I}_v - \mathbf{1}_v \mathbf{1}_v' / v) , \qquad (9)$$

and comparing the i-th diagonal elements on the two sides of (9) leads to the equality

$$r_i - v_1 r_i - v_2 r_i + \rho r_i^2 = \alpha (1 - 1/\nu)$$
 (10)

Hence

$$(r_i - r_{i'})[1 - v_1 - v_2 + \rho(r_i + r_{i'})] = 0$$
 for every  $i, i' = 1, ..., v, i \neq i'$ . (11)

It is clear that (10) also entails the inequality  $1 - v_1 - v_2 + \rho r_i > 0$ . Consequently, the expression in brackets in (11) is positive, which leads to (c).

For designs with C-matrices of the form (6), relationships between the properties of efficiency balance and commutativity, defined by

$$\mathbf{N}_1\mathbf{K}_1^{-1}\mathbf{N}_1'\mathbf{R}^{-1}\mathbf{N}_2\mathbf{K}_2^{-1}\mathbf{N}_2' = \mathbf{N}_2\mathbf{K}_2^{-1}\mathbf{N}_2'\mathbf{R}^{-1}\mathbf{N}_1\mathbf{K}_1^{-1}\mathbf{N}_1' \ ,$$

or, equivalently

$$\mathbf{A}_1 \mathbf{A}_2 = \mathbf{A}_2 \mathbf{A}_1 \ ,$$

where

$$\mathbf{A}_h = \mathbf{R}^{-1/2} \mathbf{C}_h \mathbf{R}^{-1/2}$$
,  $h = 0, 1, 2$ ,

is given in Theorem 5 below.

Theorem 5. A connected two-way elimination of heterogeneity design with equal row sizes, equal column sizes, and such that  $\mathbf{C} = \mathbf{R} - \mathbf{v}_1 \mathbf{N}_1 \mathbf{N}_1' - \mathbf{v}_2 \mathbf{N}_2 \mathbf{N}_2' + \rho \mathbf{r} \mathbf{r}'$  for some  $\mathbf{v}_1, \mathbf{v}_2, \ \rho > 0$  is efficiency-balanced if and only if it satisfies the commutativity property  $\mathbf{A}_1 \mathbf{A}_2 = \mathbf{A}_2 \mathbf{A}_1$  and the value of  $\mathbf{v}_1 k_1 \varphi_{1i} + \mathbf{v}_2 k_2 \varphi_{2i}$  is the same for i = 1, ..., v-1, where the nonzero eigenvalues  $\varphi_{h1}, ..., \varphi_{h,v-1}$ , h = 1, 2, are ordered correspondingly to a fixed set of common eigenvectors of  $\mathbf{A}_1$  and  $\mathbf{A}_2$ .

Proof. It is clear that (7) may be reformulated as

$$\mathbf{A} = \mathbf{v}_1 k_1 \mathbf{A}_1 + \mathbf{v}_2 k_2 \mathbf{A}_2 - \rho n \mathbf{A}_0 , \qquad (12)$$

where

$$A = R^{-1/2}CR^{-1/2}$$
.

Postmultiplying in (6) by  $\mathbf{1}_v$  leads to the equality  $\mathbf{0} = (1 - v_1 k_1 - v_2 k_2 + \rho n)\mathbf{r}$ , and hence

$$\rho n = v_1 k_1 + v_2 k_2 - 1 . \tag{13}$$

Substituting (13) into (12) yields

$$\mathbf{A}_0 - \mathbf{A} = v_1 k_1 (\mathbf{A}_0 - \mathbf{A}_1) + v_2 k_2 (\mathbf{A}_0 - \mathbf{A}_2)$$
,

which implies that, for every i = 1,...,v-1,

$$1 - \varphi_i = v_1 k_1 (1 - \varphi_{1i}) + v_2 k_2 (1 - \varphi_{2i}) . \tag{14}$$

In view of (12), if  $\mathbf{A} = \varepsilon \mathbf{A}_0$ , then  $v_1k_1\mathbf{A}_1 + v_2k_2\mathbf{A}_2 = (\varepsilon + \rho n)\mathbf{A}_0$ , which clearly implies that  $\mathbf{A}_1\mathbf{A}_2 = \mathbf{A}_2\mathbf{A}_1$  and  $v_1k_1\phi_{1i} + v_2k_2\phi_{2i} = \varepsilon + n\rho$  for  $i=1,2,...,\nu-1$ . Conversely, if  $\mathbf{A}_1\mathbf{A}_2 = \mathbf{A}_2\mathbf{A}_1$  and  $v_1k_1\phi_{1i} + v_2k_2\phi_{2i}$  is constant, then (14) shows that the eigenvalues  $\phi_1,...,\phi_{\nu-1}$  of  $\mathbf{A}$  are all equal, i.e.  $\mathbf{A}$  is a scalar multiple of  $\mathbf{A}_0$ .

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